

Wheeled Mobile Robot: Design And Implementation Of Wheeled Mobile Robot Using Intelligent Controllers By Mohammed Zeki Al-Faiz

By Mohammed Zeki Al-Faiz

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This paper presents a novel implementation of an integral sliding-mode controller (ISMC) on a two-wheeled mobile robot (2 WMR). The 2 WMR consists of two wheels in

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http://portal.psz.utm.my/div/bsp/images/stories/senaraitugas/ubp_cite_utm_pub_82_09.xls

There are only two types of mobile robots, If your four wheeled robot encounters uneven terrain, With a three wheel design,

http://www.societyofrobots.com/robot_omni_wheel.shtml

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model and control strategy for a Nonholonomic Wheeled Mobile Robot and intelligent controllers for the ship Al doped Si film was

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<http://www.iaeng.org/publication/WCECS2007/>

The considered two-wheeled mobile robot is shown in Fig. 1, Design of controller. For the robot shown in Fig. 1, the following controller is considered,

<http://www.sciencedirect.com/science/article/pii/S0736584509001124>

Wheeled mobile robots 77 system. The second approach is, however, more systematic and simpler, not least because of the conciseness of the notation used.

<http://www.tandfonline.com/doi/pdf/10.1163/1568553053020241>

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<http://dl.acm.org/citation.cfm?id=1825865&prelayout=flat>

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http://www.academia.edu/1431618/Alternans_lowers_the_scaling_exponent_of_heartbeat_fluctuation_dynamics_in_animal_models_and_humans

The wheeled mobile robot has been widely used in various fields nowadays. Combining with a contest of mobile robot used for sorting and conveying objects, this paper

<http://www.scientific.net/AMR.902.207>

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<http://academic.research.microsoft.com/Keyword/45185/Wheeled-Mobile-Robot>

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